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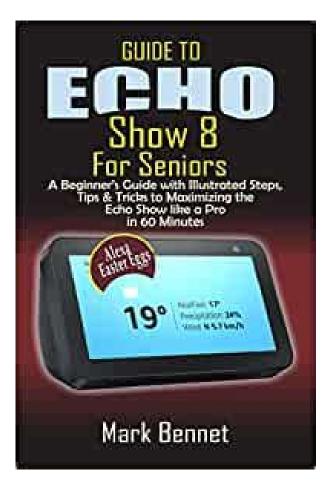
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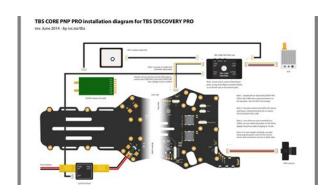
### **Book Descriptions:**

# bst pro mark manual



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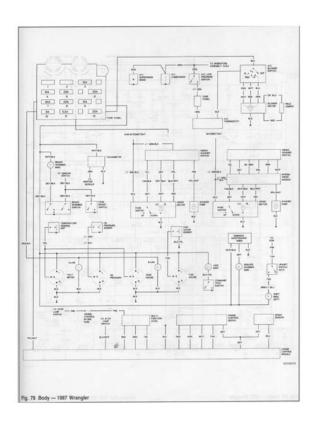
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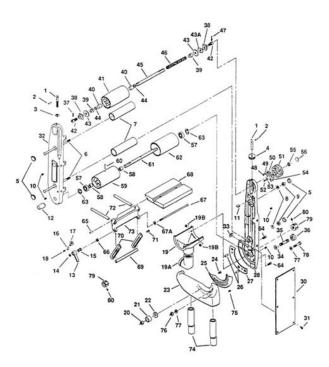


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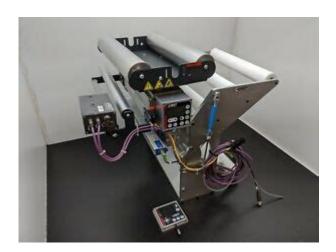
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Do not press down on the cable insert. Display has 6 lines, each of 28 characters. The graphics display is used for displaying the operating hours, parameters and the setup menus. Keypad The controller can be configured for operation using this keypad. The associated abbreviated names are displayed at the bottom edge of the screen. Press the relevant Fkey several times to select the required numerical value. The time interval in between pressing the button twice must never exceed 0.5 seconds. This can also be realised using the Fkeys. 1. Open the required submenu and then press the ENTER key to activate the editing box. 2. Now use the vertical arrow keys so that the minus sign is entered or removed. After this, enter the digit sequence as described above. B 2.2.2 Arrow keys Various entries can be made and options can be selected from the menu mode dialog windows. These give the operator reports about the current status of the components e.g. The required parameters have already been entered if the control system is an integral part of a projected BST system. You do not have to reset anything with regard to this. The CAN device address setting up is carried out via the S1 BCD switch on the processor board BCD switch S1. Procedure 1. Switchoff the

power to the controller. S1 BCD switch 2. The possible settings are described below. B 3.3.2.1 ekrPro Com In the ekrPro Com, the activation is carried out using switch S3 on the processor circuit board. BST International GmbH is not liable for damage arising from the incorrect use of the passwords. An automatic logout time can be set for all user levels timeout time. Confirm the selection by pressing ENTER. The direction has to be set for it. 1. Select the subdirectory Direction from the menu Actuator. Confirm the selection by pressing ENTER. If necessary, the actuator guiding direction for manual mode can be reversed by activating the checkbox Mot. Select x checkbox active to do this. The description is given in section 2.

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The material setup is the same for all three sensors. You must check, without fail, using a suitable test unit ohmmeter that no short circuits or crossconnections between the two windings exist before starting the commissioning. This functionality is only effective once prepositioning has been activated. These functions deal with the Tear Off Detection and Oscillation. B 3.5.8.1 TearOff Det. If necessary, a different sensor can be allocated as the tearoff detection sensor for each guiding mode. It is also possible to allocate two different guiding modes with different parameters to a single sensor. Params Addon and confirm with ENTER. 2. The menu structure is shown in Appendix D1. B 3.7.1 Change User Selection of user level User administration in the ekrPro Com differentiates between four different user levels with different user rights. The following procedures are provided for the different operating modes. However, the default values should be loaded before the special parameters are set up. Any remote control which may possibly be running, must be deactivated. The preset actuator is the EMS 17. Confirm the respective selection by pressing ENTER. Confirm the respective selection by pressing ENTER. 2. Use the horizontal left or right arrow keys in the newly not connected opened window to select the servocenter component selection window and confirm it by pressing ENTER. This enables you to limit the actuator paths. 1. In this case the centre position setting option and the gain have to be set up for the SC operating mode. If a reflection sensor is being used as Sensor 3 then only this sensor must be selected and entered from the option list. This activation of this function is a default setting. It must be deactivated if a tachogenerator is being used. 1. A stepping motor drives the sensor adjustment unit. The stepping motor output stages are not protected against short circuits.

They are the basis for displaying the traversing movement in the operating status screen. 1. Select Range from the subdirectory and then press ENTER to open the inputting menu. In this case, each FVG needs to be adjusted separately. The terms used here FVG 1 Slide 1 and FVG 2 Slide 2 relate to the arrangements in accordance with Point A 1.4.5. This reference point can, for example, be the machine wall or another obvious point on the machine. It is also possible to use an outer position or the centre of the FVG. They are the basis for displaying the traversing movement in the operating status screen. The manufacturer has entered this default setting and you are only permitted to modify it if necessary after having obtained the manufacturer's agreement. This standardisation mode is normally used Select a norming mode for the infrared sensor IR 2002 with Bright. Outer material web generally occurs from the outside. The FVG operating mode can be carried out in the MAN mode, in the Automatic mode as well as the SC mode. These can be accepted as is or adapted to the application. 3. The measuring unit is mm. This will open up the input window. 2. Enter the nominal value for the material width in the edit field Nominal Width. 3. Enter selected values for the error and warning limits in the corresponding edit fields. Therefore each scanning mode can have the input signal of any sensor allocated to it. To activate normalized display, select checkbox norm. 10. If necessary, the checkbox inv.Both contain various assignments for the digital inputs see Point B 3.7.5.9.3. In so doing, the standard bitpattern for lines 29 and 30 must not be changed. 1. Select Dig. IO in General Setup and then select the Inputs subdirectory afterwards. The following section of the

truth table shows that lines 21 and 22 belong to a bitblock with a total of 8 lines lines 21 to 28. Factory allocation of functions with the corresponding standard bitpatterns Terminal.

As the function tearoff detection requires only lines 21 and 22 of the bit block, the factoryside allocation of functions to the remaining lines of the block lines 23 to 28 must be cancelled. Accordingly the function Do Nothing is allocated to lines 23 to 28 from the option list. The meaning of the individual messages can be taken from the table on the following page. 1. Width warn min. Web width measurement Web width has fallen below the lower warning limit. Width warn max. A defined state is set up when the unit is reset. The separate windows can still be called up even if an optional logic module has not been integrated, but you cannot make any entries. The function Unit remote control allows to operate the controllers available in the system from different sources e.g. The maximum individual contact nominal current is 4A. Contact assignments in the plug connector View on the screw side Socket Plug female Display has 6 lines, each of 28 characters. Keypad The controller can be configured for operation using this keypad. Therefore a menu option can be selected by using the arrow keys to navigate to the required menu suboption or it can be selected directly by using the shortcut number instead. For example Selecting the actuator The associated menu suboption is 611 see navigation overview as well. This can also be realised using the Fkeys. 1. Open the required submenu and then press the ENTER key to activate the editing box. 2. This is realised by pressing the ENTER button to open the selected option list. Example Select an actuator type Select an actuator type EMS 10 EMS 17 EMS 16 EMS 17. Width Measure Offset current width Selected digit Opened 78.5 enter ref.width editing box Use the horizontal arrow keys to position the cursor on the number to be modified. Use the vertical arrow keys to change between the different displays in normal control mode. Current position value for sensors Accept current position value as new setpoint for active guiding mode.

Web center guiding Press the "SENSOR LEFT". The operating status display settings are described in the following. The system must be in "AUTO" mode. Press the SETUP button and the parameters displayed in the line at the bottom of the screen will change from the displayed setpoint W to the gain setting XP. The material setup is the same for all three sensors. This is different dependent on whether the sensor is being used for line sampling or for contrast sampling. In addition to the normal material setup, the offset value and gain for sensor 3 can also be set here. If an outward or inward tear is detected, this is indicated in the display by an exclamation mark. As soon as the guiding system is blocked, a lock appears in the actuator symbol. Both the guiding mode on which the prepositioning is to be used and the target web position itself can be set. The predefined machine centreline is calculated from the offset value settings which were defined during the startup procedure see Point B 3.7.5.5.4 and example below. You can chose to display them or suppress them. Furthermore, the display duration of a reported error can be varied.MOTOR OVERCURRENT blocking the motorised guide. Error report will be deleted automatically. Actuator short circuit Find the cause of the short MOTOR SHORT CIRCUIT The actuator controller was circuit. If necessary clean sensor. NORMING ERROR No guidance is possible. Insert material and repeat sensor normalisation. During edge detection the Insert material and repeat edge FVG slide has reached the detection. Remove the to any operation. Cleaning should be carried out using a dry, clean and soft cloth. A commercial liquid cleaner may be used if the casing is very dirty. Adhere to protection class IP 54. Beware! The controller has to be switched off! C 4.2 Sensors. The following settings are set up again after a reset has been carried out Parameter Level 3 Default Value Menu Parameter Level 1 Parameter Level 2 Change User User Level.

Mode not connected Int.Functions Tear Off Det.Logic Params 1 Params 2 Fieldbus Status Bus type unknown Module status Data exchange not running Last interrupt Profibus Address Swap Bytes Swap Words DeviceNet Address Baudrate 500 kbps. The details in this section refer to the special components with information about the menus that have to be used or setting up windows. Check to

ensure that the percentage display value increases the more the sensor is covered. If not, check whether inverting is set. After this, the Master setup for this sensor has to be carried out. To learn more about how we protect and manage your submitted data, please visit our Privacy Policy. Through integration, you can leverage our strong project management capabilities, while utilizing your existing system to manage financials. All Rights Reserved. Octopus Suite Outstanding FeaturesDirect Unlock. Repair IMEI. Repair TASpecial environmental bonding glue handicraf. We hope that youll continue to give us valuable feedback on your shopping. Base station BreezeMAX 2300 System Manual. SW Version 4.0. October 2006. Rev.ADocument History. Topic. Description. First Release. New Product Manual. September 2006BreezeMAX Modular Base Station System ManualLegal Rights. The material contained herein is proprietary, privileged, and confidential andNo disclosure thereof shall be madeAlvarion Ltd. reserves the right to alter the equipment specifications andNo part of this publicationTrade NamesAll other names are or may be the trademarks of their respective owners. Statement of Conditions. The information contained in this manual is subject to change without notice. Alvarion Ltd. shall not be liable for errors contained herein or for incidental orWarranties and Disclaimers.

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principles of defining Service Profiles for 3rd party generic non. DRAP based VoIP devices. Chapter 1 System Description Chapter 2 Installation Guidelines Breeze MAX Modular Base Station System Manual Chapter 3 Commissioning Breeze MAX Modular Base Station System Manual Chapter 4 Operation and Administration Breeze MAX Modular Base Station System Manual Breeze MAX Modular Base Station System Manual Before you Start. 232. A.2 File Loading Procedure. 233. A.3 Completing the Software Upgrade Switching Versions. 235. B.1 Introduction. 238. B.1.1 Priority Marking. 238. B.1.2 General Assumptions. 238. B.2 1 POTS Basic VoIP G.729 Service Profile. 240. B.2.1 Service Characteristics. 240. B.2.2 RTP BW Calculation. 240. B.2.3 RTCP BW Calculation. 240. B.2.4 QoS Profile. 240. B.

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